Measurable Ambiguity
with Wolfgang Pesendorfer

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## A Few Definitions

A Lottery is a (cumulative) probability distribution over monetary prizes.
It is a probabilistic description of the DMs uncertain situation.
$\mathcal{L}$ is the set of all lotteries.


## A Few Definitions

A Lottery Preference is a utility function $V: \mathcal{L} \rightarrow R$ over lotteries.

- In economics, often lotteries are the primitive.
- Empirical evidence does not come in the form of lotteries.
- The relevant probabilities are estimated.
- Assumptions are made about whether or not agents know (or agree on) these probabilities.


## Definitions Continued

An Act is a nonprobabilistic description of the DMs uncertain situation.

Cloudy
100 -80

Snowy 65

An act is less abstract than a lottery. It is more like real data.

## Definitions Continued

Assessment is a the process of assigning subjective probabilities to events.

|  | .4 | .35 | .25 |
| :--- | :--- | :--- | :--- |
|  | Cloudy | Rainy | Snowy |
| f | 100 | -80 | 65 |
| g | 50 | 30 | 0 |
| h | -20 | -20 | -20 |
| $\ldots$ | $\ldots$ | $\ldots$ | $\ldots$ |
| $\cdots$ | $\cdots$ | $\cdots$ | $\cdots$ |
| $\cdots$ | $\cdots$ | $\cdots$ | $\cdots$ |

## Definitions Continued

Reduction enables the DM to interpret acts as lotteries.

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|  | Cloudy | Rainy | Snowy | Lotteries |
| f | 100 | -80 | 65 | $(.35,-80 ; .25,65 ; .4,100)$ |
| g | 50 | 30 | 0 | $(.25,0 ; .35,30 ; .4,50)$ |
| h | -20 | -20 | -20 | $(1,-20)$ |
| $\ldots$ | $\ldots$ | $\ldots$ | $\cdots$ |  |
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| $\ldots$ | $\ldots$ | $\ldots$ | $\cdots$ |  |

## Definitions Continued

A DM is Probabilistically Sophisticated if he evaluates acts $f$ through
Assessment + Reduction + Lottery Preference

$$
U(f)=V\left(G^{f}\right)
$$

Add the phrase "as if" to the above as many times as you wish.

Three Approaches of Decision-Making under Uncertainty

The Pure Subjectivist (Bayesian) Approach

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- Literature: Generalizations of EU Theory


# Three Approaches of Decision-Making under Uncertainty 

The Pure Subjectivist (Bayesian) Approach

- All events can be assigned probabilities: Subjective Expected Utility Theory
- Key Anomali: Allais Paradox, Preferences not linear in probabilities
- Literature: Generalizations of EU Theory
- "Final" Model: Machina-Schmeidler (Probabilistic Sophistication)


## Some Literature:

- Ramsey (1926)
- Savage (1954)
- All of the nonexpected utility literature
- Machina and Schmeidler (1992)

Fast Summary


You win $\$ x, \$ y$ or $\$ z$
Depending on where the dart lands

## Subjective Probabilities



- The DM assesses probabilities to all events.


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The act becomes the lottery (.5x; .3y;.2z)
Yielding utility $.5 u(x)+.3 u(y)+.2 u(z)$
Or more generally $U(.5 x ; .3 y ; .2 z)$

## Knightian Approach

Knightian uncertainty is risk that is immeasurable, not possible to calculate
Wikipedia
"Uncertainty must be taken in a sense radically distinct from the familiar notion of Risk,.... The essential fact is that 'risk' means in some cases a quantity susceptible of measurement, while at other times it is something distinctly not of this character."
F. Knight

## Some Literature:

- Knight (1921)
- Ellsberg (1961)
- Schmeidler (1989)
- Most of the ambiguity literature


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- "Final" Model: Uncertainty Averse Preferences Cerreia-Vioglio, Maccheroni, Marinacci and Montrucchio (2008)

Risky versus Ambiguous Events


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Each gray region has a third of the area

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Each gray region has a third of the area
DM prefers $E_{1}$ to $E_{2}$.

Risky versus Ambiguous Events


Each gray region has a third of the area
DM prefers $E_{1}$ to $E_{2}$.
But also $E_{2} \cup E_{3}$ to $E_{1} \cup E_{3}$.

## Fast Summary



- Every column is unambiguous


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- "susceptible of measurement"


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$E_{1}$ has probability $\frac{1}{3}$.


## Fast Summary


$E_{1}$ has probability $\frac{1}{3}$
Probability of $E_{2}$ ? ( $E_{2}$ and $E_{3}$ are ambiguous)

## Fast Summary



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- DM need not probabilistically sophisticated across environments.
- Key Anomali: Ellsberg Two-Urn Paradox
- "Final" Model: ?


## Some Literature:

- Heath and Tversky (1991)
- Abdellaoui, Baillon, Placido and Wakker (2008)
- Chew and Sagi (2008)
- Ergin and Gul (2009)
- The Home Bias Literature

Different risk aversion in different environments

## A Two-Urn Example

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Bet 1: $\$ 100$ if the color of a ball drawn from urn 1 is in the set $A, \$ 0$ otherwise.

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- The DM is probabilistically sophisticated when choosing among risky prospects that depend on balls drawn from urn 1


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- Since colors are interchangeable, we expect a decision maker to be probabilistically sophisticated when choosing among risky prospects that depend on balls drawn from urn 2 .


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- Since colors are interchangeable, we expect a decision maker to be probabilistically sophisticated when choosing among risky prospects that depend on balls drawn from urn 2 .

But the DM need not be indifferent between the Bet 1 and Bet 2 .

Objectives:

- (1) Subjective Model of Choice under Uncertainty

A (Simple) Representation for All Acts

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- (1) Subjective Model of Choice under Uncertainty

A (Simple) Representation for All Acts

- (2) Multiple Sources and Environments

Use the Framework to Address Experimental Evidence (Allais and Ellsberg)

- (3) Separate Uncertainty and Attitude to Uncertainty.

The Model

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Domain of preference: $\mathcal{F}=\{f: \Omega \rightarrow[I, m]\}$
We axiomatize Expected Uncertain Utility (EUU).

## An Example:



States: $\Omega=[0,1] \times[0,1]$
The Prior $(\mathcal{E}, \mu)$ :
$\mathcal{E}$ is smallest $\sigma$-algebra that contains all full-height rectangles (like $E$ ) and all sets that have zero Lebesgue measure on the square.
$\mu([a, b] \times[0,1])=b-a$ for $b \geq a$.

An Act, Its Envelope and Utility:


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Suppose $x<y<z$
Envelope:
$f_{1}=x$
$\mathbf{f}_{2}=y E_{1} z$

An Act, Its Envelope and Utility:


$$
U(f)=\mu\left(E_{1}\right) u(x, y)+\mu\left(E_{2}\right) u(x, z)
$$

(1) The EUU Representation

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lower bound of $f$ and $\mathbf{f}_{2}$ is the smallest measurable lower bound of $f$.
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Definition: An envelope for $f \in \mathcal{F}$ is a function $\mathbf{f}: \Omega \rightarrow I$ such that

1. $\mathbf{f}$ is $\mathcal{E}$-measurable and $\mu\left(\left\{\mathbf{f}_{1}(\omega) \leq f(\omega) \leq \mathbf{f}_{2}(\omega)\right\}\right)=1$
2. $\mathbf{g}$ satisfies $(1)$ implies $\mu\left(\left\{\mathbf{g}_{1}(\omega) \leq \mathbf{f}_{1}(\omega) \leq \mathbf{f}_{2}(\omega) \leq \mathbf{g}_{2}(\omega)\right\}\right)=1$.

Lemma 1: Let $(\mathcal{E}, \mu)$ be a prior and $f \in \mathcal{F}$. Then, $f$ has an envelope.

# Expected Uncertain Utility 

Interval utility index: a continuous function $u: I \rightarrow \mathbb{R}$ such that $u(x, y)>u\left(x^{\prime}, y^{\prime}\right)$ whenever $x>x^{\prime}, y>y^{\prime}$.

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Definition: The preference $\succeq$ is an EUU if there is a prior $(\mathcal{E}, \mu)$ and an interval utility index $u$ such that

$$
U(f)=\int u\left(\mathbf{f}_{1}(\omega), \mathbf{f}_{2}(\omega)\right) d \mu
$$

represents $\succeq$.

## Expected Uncertain Utility

Given the prior $\mu$ we can define a bicumulative over prizes for every act $f$ :

Bicumulative: Let $H_{f}(x, y)=\mu\left(\left\{\mathbf{f}_{1} \leq x, \mathbf{f}_{2} \leq y\right\}\right)$.

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U(f)=\int u(x, y) d H_{f}(x, y)
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The bicumulative is analogous to cdf over prizes in the standard case.

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Under suitable assumptions,
A preference $\succeq$ on $\mathcal{F}$ has an EUU representation:

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or equivalently

$$
U(f)=\int u(x, y) d H_{f}(x, y)
$$

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Each urn (or collection of events: rows, columns and colors) is a a source and the collection of all bets (acts) that depend on a particular source is an environment.

The DM can be more risk averse when betting on columns than when betting on colors.

## Sources and Environments

- Let $\mathcal{C}$ be a collection of sets (a $\lambda$-system).
- $\mathcal{F}_{\mathcal{C}}=\{f \in \mathcal{F}: f$ is $\mathcal{C}$ - measurable $\}$

For example, let

$$
\begin{gathered}
\mathcal{C}_{1}=\{\mathrm{G}(\text { ray }), \mathrm{O}(\text { range }), \mathrm{Y}(\text { ellow }), \mathrm{P}(\text { each })\} \\
\mathcal{C}=\{\text { all events that depend only on color, } \mathrm{G}, \mathrm{Y}, \mathrm{G} \cup \mathrm{Y} \text { etc. }\} \\
\mathcal{F}_{\mathcal{C}}=\{\text { all acts that depend only on color }\}
\end{gathered}
$$

- Suppose each color has the same probability and each column $K_{i}$ has the same probability $(1 / 4)$.
- Consider the two bets: $100 Y 0$ and $100 K_{1} 0$.
- Suppose the DM utility function satisfies

$$
U(40)=U(100 Y 0)>U\left(100 K_{1} 0\right)=U(35)
$$

Hence, the DM prefers betting on color to betting on column.
Equivalently the DM is more risk averse when betting on columns than when betting on colors.

- If $(\mathcal{C}, \pi)$ is a probability measure (Assessment), then each $f \in \mathcal{F}_{\mathcal{C}}$ can be assigned a cdf (Lottery) $G^{f}$ (Reduction).
- The Assessment) makes $f \in \mathcal{F}_{\mathcal{C}}$ into a source and $\mathcal{F}_{\mathcal{C}}$ into an environment.
- Then, the DM has a lottery preference $V$ so that he assigns utility $V\left(G^{f}\right)$ to each $f$

Whether or not $\mathcal{F}_{\mathcal{C}}$ is an environment is subjective as is the lottery preference $V$ on $\mathcal{F}_{\mathcal{C}}$.

## Sources, Environments and EUU

- So far, the definitions of Source and Environment don't require EUU preferences.
- How many sources does a typical EUU preference have?
- What kind of lottery preferences does an EUU preference have in these environments?
- How do these environments enable EUU theory to address experimental and empirical evidence (Allais, Ellsberg, Home Bias)?
(2) Multiple Sources and Environments in EUU Theory


## Definition: $u$ is strongly symmetric if it has the form

$$
u(x, y)=(v(x)+v(y)) / 2
$$

for some $v$.
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Lemma 3: If $\mathcal{F}_{\mathcal{C}}$ is an environment for the $\operatorname{EUU}(\mathcal{E}, \mu, u)$ and $u$ is not strongly symmetric, then it is an environment every EUU with the same prior.
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- EUU's with the same prior have (essentially) the same environments.
- This is the sense in which (3) Separation is achieved.
- We call $\mathcal{F}_{\mathcal{C}}$ a Regular Environment for $(\mathcal{E}, \mu)$ if it is an environment for some $(\mathcal{E}, \mu, u)$ with $u$ not strongly symmetric.


## Multiple Environments

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- model source preference ("home bias");
- match Ellsberg-type evidence.
- address Allais-type evidence.


## Multiple Environments: Some Properties

- Every EUU has every source.
- The prior alone determines if $\mathcal{F}_{\mathcal{C}}$ is an environment for $(\mathcal{E}, \mu, u)$
- Risk attitude depends $u$.
- One environment for the the $\operatorname{EUU}(\mathcal{E}, \mu, u)$ is $\mathcal{F}_{\mathcal{E}}$, the Ideal environment.
- Every EUU is an expected utility maximizer in its ideal environment.

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U(f)=\int u(f(\omega), f(\omega)) d \mu
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- In other environments, the $\operatorname{EUU}(\mathcal{E}, \mu, u)$ is a nonexpected utility maximizer

Regular Environments and Lottery Preferences for EUU

Proposition 2: For any interval utility $u$, there exists a sequence of lottery preferences $V_{n}^{u}$ and for any regular environment $\mathcal{F}_{\mathcal{C}}$ of $(\mathcal{E}, \mu)$, there exists a sequence $a_{n} \geq 0, \sum a_{n}=1$ such that

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U(f)=V\left(G^{f}\right)=\sum_{n} a_{n} V_{n}^{u}\left(G^{f}\right)
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represents $(\mathcal{E}, \mu, u)$. Furthermore, for any such sequence $a_{n}$ and $(\mathcal{E}, \mu)$, there exists a regular environment $\mathcal{F}_{\mathcal{C}}$ such that

$$
U(f)=\sum_{n} a_{n} V_{n}\left(G^{f}\right)
$$

for all $f \in \mathcal{F}_{\mathcal{C}}$.

Allais and Uncertainty Aversion

Allais Paradox:

$$
V(100)>V(150,4 / 5 ; 0,1 / 5)
$$

but
$V(100,2 / 5 ; 0,3 / 5)<V(150,1 / 2 ; 0,1 / 2)$

## Allais Reversals

Definition: A lottery preference $V$ is prone to Allais-reversals if there is an environment $\gamma$ so that we can find

- a lottery $F$
- prizes $x, y$ where $x$ is weakly worse than all other prizes in the support of $F$
- $\alpha \in(0,1)$


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so that we have
- $V(y)>V(F)$
- $V(\alpha y+(1-\alpha) x)<V(\alpha F+(1-\alpha) x)$.


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RDEU: The lottery preference $V: \mathcal{L} \rightarrow R$ is an RDEU if

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V(F)=\int v(x) d \gamma(F(x))
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for some PTF $\gamma$.

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PTF: $\gamma:[0,1] \rightarrow[0,1]$ is a probability transformation function if it is continuous, onto and strictly increasing.
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for some PTF $\gamma$.
PTF's that have an inverted $S$-shape are (a) consistent with Allais reversals and (b) have some supporting experimental evidence (Starmer (2000)).

# Polynomial Utility and Special Cases 

Recall: A sequence $a_{n} \geq 0$ such that $\sum_{n} a_{n}=1$ characterizes a regular environment and in each environment $\left\{a_{n}\right\}$ the EUU with interval utility $u$ has lottery preference

$$
U(f)=\sum_{n} a_{n} V_{n}^{U}\left(G^{f}\right)
$$

We call the sequence $a_{n}$ the uncertainty measure of the corresponding environment.

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- More generally, whenever $u(x, y)=\alpha v(x)+(1-\alpha) v(y)$ for some $v$, every environment is an RDEU environment. This RDEU has the desired inverted $S$-shape whenever $\left\{a_{n}\right\}$ is sufficiently uncertain.
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- $V_{2}^{u}$ is the quadratic utility of Machina (1982), Chew, Epstein and Segal (1991) (with utility index $u$ ). Hence, $a_{2}=1$ is the quadratic utility environment.


## Strong Uncertainty Aversion

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- $u$ is maximally pessimistic if there exist some $v$ such that $u(x, y)=v(x)$ for all $x, y$.

Proposition 3: Let $(\mathcal{E}, \mu, u)$ be an EUU. Then, the following conditions are equivalent
(1) The EUU $(\mathcal{E}, \mu, u)$ is strongly uncertainty averse;
(2) $u$ is maximally pessimistic and concave.

## Uncertainty of Environments

Definition: The environment $\mathcal{F}_{\mathcal{A}}$ is more uncertain than the environment $\mathcal{F}_{\mathcal{B}}$ if every strongly uncertainty averse EUU prefers $f \in \mathcal{F}_{\mathcal{A}}$ to $g \in \mathcal{F}_{\mathcal{B}}$ whenever $f$ and $g$ yield the same lottery.

Proposition 4: $\mathcal{F}_{\mathcal{B}}$ more uncertain than $\mathcal{F}_{\mathcal{A}}$ if and only if

$$
\sum_{n} b_{n} t^{n} \leq \sum_{n} a_{n} t^{n}
$$

for all $t \in[0,1]$, where $\left\{a_{n}\right\}$ and $\left\{b_{n}\right\}$ are the uncertainty measures of $\mathcal{F}_{\mathcal{A}}$ and $\mathcal{F}_{\mathcal{B}}$ respectively.

- We write $\mathcal{F}_{\mathcal{B}} \succeq_{m u} \mathcal{F}_{\mathcal{A}}$ (or equivalently $\left\{b_{n}\right\} \succeq_{m u}\left\{a_{n}\right\}$ ) to mean " $\mathcal{F}_{\mathcal{B}}$ is more uncertain than $\mathcal{F}_{\mathcal{A}}$."
- $b_{n+1}=1$ and $a_{n}=1$ implies $\left\{b_{n}\right\} \succeq_{m u}\left\{a_{n}\right\}$.
- Not all environments can be ranked. For example, $a_{2}=1$ and $a_{1}=a_{4}=1 / 2$ cannot be ranked.

Risk Loving under Extreme Uncertainty:

The EUU is risk loving under extreme uncertainty if, for sufficiently uncertain environments, there are lotteries that the DM prefers to their expected value.

Definition $u$ displays risk loving under extreme uncertainty if there exists an environment $\mathcal{F}_{\mathcal{A}}$ and a lottery $F$ such that $\mathcal{F}_{\mathcal{B}} \succeq_{m u} \mathcal{F}_{\mathcal{A}}$ implies $U(f)>U(z)$ whenever $f \in \mathcal{F}_{\mathcal{B}}, G^{f}=F$ and $z$ is the mean of $F$.

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Ellsberg One Urn Example

3 balls, red, blue or green. 1 ball is red. Intuitively, $\{r\}$ and $\{b, g\}$ have unambiguous probability $1 / 3$ and $2 / 3$. But, $\{g\}$ and $\{r, b\}$ are ambiguous.
What would it mean for a model (an EUU model) to explain or rationalize the Ellsberg One-Urn Example?

- $N$ is a nonempty finite set; $\mathcal{N}$ is the set of subsets of $N$.
- $P$ be the set of all probabilities on $\mathcal{N}$ and $\iota \in P$.
- $\mathcal{M} \subset \mathcal{N}$ is a collection of sets (a $\lambda$-system).

The collection $(N, \mathcal{M}, \iota)$ is an urn experiment if for all $K \in \mathcal{N} \backslash \mathcal{M}$, there exist $p \in P$ such that $p(M)=\iota(M)$ for all $M \in \mathcal{M}$ and $p(K) \neq \iota(K)$.
Given any prior $(\mathcal{E}, \mu)$, a collection of subsets $\mathcal{C}_{o}$ of $\Omega$ is unambiguous if there exists a source $\mathcal{A}$ such that $\mathcal{C}_{o} \subset \mathcal{A}$. The event $A \subset \Omega$ is ambiguous wrt $\mathcal{C}_{0}$ if there exists no source $\mathcal{B}$ such that $\mathcal{C}_{O} \cup\{A\} \subset \mathcal{B}$.

Ellsberg One Urn Example is an Urn Example

$$
\begin{aligned}
& \mathcal{M}=\{\{r\},\{b, g\}\} \\
& \iota \text { is any probability such that } \iota\{r\}=1 / 3 \text { and } \iota\{b, g\}=2 / 3
\end{aligned}
$$

Zhang's (1997) 4 color urn

2 balls: red, blue, green, or yellow.
1 balls is red or blue
1 ball is red or green.

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1 balls is red or blue
1 ball is red or green.
Intuitively unambiguous events are $\{r, b\},\{g, y\},\{r, g\},\{b, y\}$ and each has $\iota=1 / 2$.

## Rationalizing Urn Experiments

The prior $(\mathcal{E}, \mu)$ rationalizes the urn experiment $(N, \mu, \iota)$ if there exists an onto mapping $T: \Omega \rightarrow N$ such that $\mathcal{C}_{0}:=\left\{T^{-1}(M) \mid M \in \mathcal{M}\right\}$ is unambiguous and every $T^{-1}(L)$ for $L \in \mathcal{N} \backslash \mathcal{M}$ is ambiguous wrt $\mathcal{C}_{o}$.

Proposition 6: Every prior rationalizes every urn experiment.

## Conclusion

Expected Uncertain Utility theory is a simple extension of Subjective
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EUU has:

- significant overlap with many existing models (Choquet EU, Maxmin EU, $\alpha$-Maxmin EU.)
- few behavioral restrictions; more of a framework than a "theory."

