Measurable Ambiguity

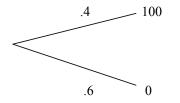
with Wolfgang Pesendorfer

August 2009

A Few Definitions

A Lottery is a (cumulative) probability distribution over monetary prizes. It is a probabilistic description of the DMs uncertain situation.

 $\mathcal L$ is the set of all lotteries.



A Few Definitions

A Lottery Preference is a utility function $V : \mathcal{L} \rightarrow R$ over lotteries.

- ▶ In economics, often lotteries are the primitive.
- Empirical evidence does not come in the form of lotteries.
- The relevant probabilities are estimated.
- Assumptions are made about whether or not agents know (or agree on) these probabilities.

An Act is a nonprobabilistic description of the DMs uncertain situation.

Cloudy	Rainy	Snowy
100	-80	65

An act is less abstract than a lottery. It is more like real data.

Assessment is a the process of assigning subjective probabilities to events.

	.4	.35	.25	
	Cloudy	Rainy	Snowy	
f	100	-80	65	
g	50	30	0	
h	-20	-20	-20	

Reduction enables the DM to interpret acts as lotteries.

	.4	.35	.25	
	Cloudy	Rainy	Snowy	Lotteries
f	100	-80	65	(.35, -80; .25, 65; .4, 100)
g	50	30	0	(.25, 0; .35, 30; .4, 50)
h	-20	-20	-20	(1, -20)
	•••	•••		
	•••	•••		

A DM is Probabilistically Sophisticated if he evaluates acts f through Assessment + Reduction + Lottery Preference

 $U(f) = V(G^f)$

Add the phrase "as if" to the above as many times as you wish.

The Pure Subjectivist (Bayesian) Approach

 All events can be assigned probabilities: Subjective Expected Utility Theory

The Pure Subjectivist (Bayesian) Approach

- All events can be assigned probabilities: Subjective Expected Utility Theory
- Key Anomali: Allais Paradox, Preferences not linear in probabilities

The Pure Subjectivist (Bayesian) Approach

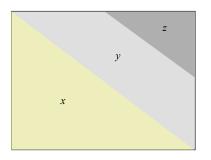
- All events can be assigned probabilities: Subjective Expected Utility Theory
- Key Anomali: Allais Paradox, Preferences not linear in probabilities
- ► Literature: Generalizations of EU Theory

The Pure Subjectivist (Bayesian) Approach

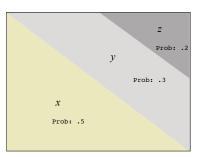
- All events can be assigned probabilities: Subjective Expected Utility Theory
- Key Anomali: Allais Paradox,
 Preferences not linear in probabilities
- ► Literature: Generalizations of EU Theory
- "Final" Model: Machina-Schmeidler (Probabilistic Sophistication)

Some Literature:

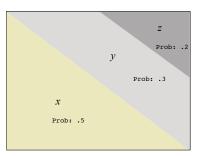
- ▶ Ramsey (1926)
- ► Savage (1954)
- ► All of the nonexpected utility literature
- Machina and Schmeidler (1992)



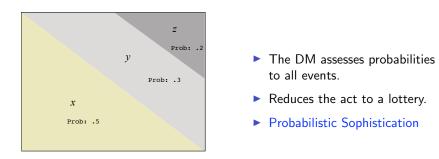
You win \$*x*, \$*y* or \$*z* Depending on where the dart lands



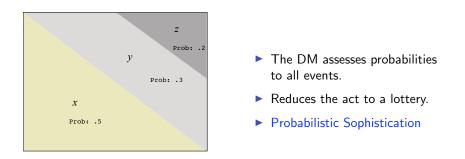
 The DM assesses probabilities to all events.



- The DM assesses probabilities to all events.
- Reduces the act to a lottery.



The act becomes the lottery (.5x; .3y; .2z)



The act becomes the lottery (.5x; .3y; .2z)Yielding utility .5u(x) + .3u(y) + .2u(z)Or more generally U(.5x; .3y; .2z)

Knightian Approach

Knightian uncertainty is risk that is immeasurable, not possible to calculate. Wikipedia

"Uncertainty must be taken in a sense radically distinct from the familiar notion of Risk,.... The essential fact is that 'risk' means in some cases a quantity susceptible of measurement, while at other times it is something distinctly not of this character." F. Knight

Some Literature:

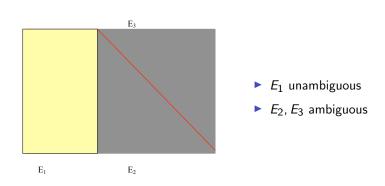
- Knight (1921)
- Ellsberg (1961)
- Schmeidler (1989)
- Most of the ambiguity literature

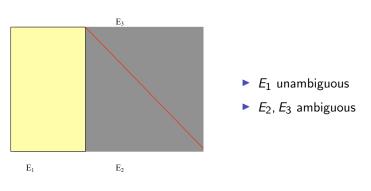
Some events have (subjective or objective) probabilities, others don't.

- Some events have (subjective or objective) probabilities, others don't.
- Ambiguity is a property of a single event.

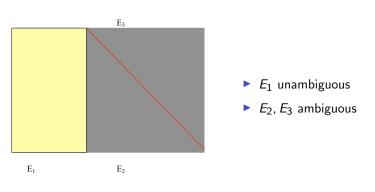
- Some events have (subjective or objective) probabilities, others don't.
- Ambiguity is a property of a single event.
- Key Anomali: Ellsberg Single-Urn Paradox Probabilities are not additive.

- Some events have (subjective or objective) probabilities, others don't.
- Ambiguity is a property of a single event.
- Key Anomali: Ellsberg Single-Urn Paradox Probabilities are not additive.
- "Final" Model: Uncertainty Averse Preferences Cerreia-Vioglio, Maccheroni, Marinacci and Montrucchio (2008)



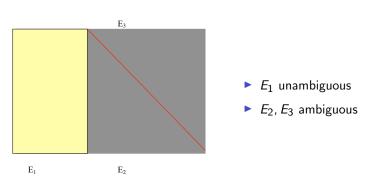


Each gray region has a third of the area.



Each gray region has a third of the area.

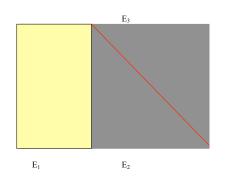
DM prefers E_1 to E_2 .



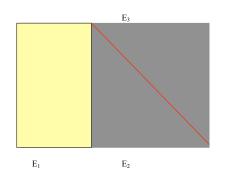
Each gray region has a third of the area.

DM prefers E_1 to E_2 .

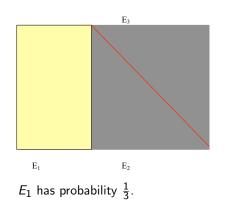
But also $E_2 \cup E_3$ to $E_1 \cup E_3$.



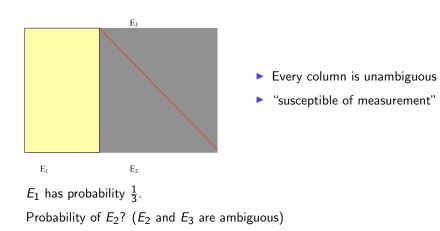
• Every column is unambiguous

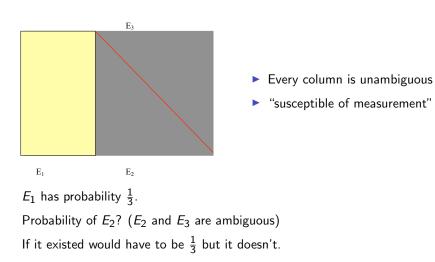


- Every column is unambiguous
- "susceptible of measurement"



- Every column is unambiguous
- "susceptible of measurement"





Not all probabilities are equal.

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- ► Riskiness is a property of a collection of events.

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- Riskiness is a property of a collection of events.
- A DM may be indifferent between A and A^c ; B and B^c .

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- Riskiness is a property of a collection of events.
- A DM may be indifferent between A and A^c ; B and B^c .
- But not between A and B.

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- Riskiness is a property of a collection of events.
- A DM may be indifferent between A and A^c ; B and B^c .
- But not between A and B.
- A DM may probabilistically sophisticated over multiple collections of events (sources).

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- Riskiness is a property of a collection of events.
- A DM may be indifferent between A and A^c ; B and B^c .
- But not between A and B.
- A DM may probabilistically sophisticated over multiple collections of events (sources).
- > DM need not probabilistically sophisticated across environments.

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- Riskiness is a property of a collection of events.
- A DM may be indifferent between A and A^c ; B and B^c .
- But not between A and B.
- A DM may probabilistically sophisticated over multiple collections of events (sources).
- > DM need not probabilistically sophisticated across environments.
- ► Key Anomali: Ellsberg Two-Urn Paradox

- ► Not all probabilities are equal.
- Multiple ways to split-up the event space into unambiguous events.
- Riskiness is a property of a collection of events.
- A DM may be indifferent between A and A^c ; B and B^c .
- But not between A and B.
- A DM may probabilistically sophisticated over multiple collections of events (sources).
- > DM need not probabilistically sophisticated across environments.
- ► Key Anomali: Ellsberg Two-Urn Paradox
- ► "Final" Model: ?

Some Literature:

- ► Heath and Tversky (1991)
- Abdellaoui, Baillon, Placido and Wakker (2008)
- Chew and Sagi (2008)
- ► Ergin and Gul (2009)
- The Home Bias Literature
 Different risk aversion in different environments

A Two-Urn Example

Urn 1: *n*-colors, 1 ball for each color;

Bet 1: 100 if the color of a ball drawn from urn 1 is in the set A, 0 otherwise.

A Two-Urn Example

Urn 1: *n*-colors, 1 ball for each color;

Bet 1: 100 if the color of a ball drawn from urn 1 is in the set A, 0 otherwise.

intuitively, only the cardinality of the set A should matter. Therefore, we can define Pr(A) = #A/n and Pr(A) should be all that matters for the DM.

A Two-Urn Example

Urn 1: *n*-colors, 1 ball for each color;

Bet 1: 100 if the color of a ball drawn from urn 1 is in the set A, 0 otherwise.

- ▶ intuitively, only the cardinality of the set A should matter. Therefore, we can define Pr(A) = #A/n and Pr(A) should be all that matters for the DM.
- The DM is probabilistically sophisticated when choosing among risky prospects that depend on balls drawn from urn 1.

Urn 2: *n* balls, *n* possible colors, no further information.

Urn 2: *n* balls, *n* possible colors, no further information.

Bet 2: \$100 if the color of a ball drawn from urn 2 is in the set A, \$0 otherwise.

Urn 2: *n* balls, *n* possible colors, no further information.

Bet 2: 100 if the color of a ball drawn from urn 2 is in the set A, 0 otherwise.

As in the case of urn 1, we can define Pr(A) = #A/n and only Pr(A) should matter for the ranking of bets

Urn 2: *n* balls, *n* possible colors, no further information.

Bet 2: \$100 if the color of a ball drawn from urn 2 is in the set A, \$0 otherwise.

- As in the case of urn 1, we can define Pr(A) = #A/n and only Pr(A) should matter for the ranking of bets
- Since colors are interchangeable, we expect a decision maker to be probabilistically sophisticated when choosing among risky prospects that depend on balls drawn from urn 2.

Urn 2: *n* balls, *n* possible colors, no further information.

Bet 2: \$100 if the color of a ball drawn from urn 2 is in the set A, \$0 otherwise.

- As in the case of urn 1, we can define Pr(A) = #A/n and only Pr(A) should matter for the ranking of bets
- Since colors are interchangeable, we expect a decision maker to be probabilistically sophisticated when choosing among risky prospects that depend on balls drawn from urn 2.

But the DM need not be indifferent between the Bet 1 and Bet 2.

Objectives:

- (1) Subjective Model of Choice under Uncertainty
 - A (Simple) Representation for All Acts

Objectives:

- ▶ (1) Subjective Model of Choice under Uncertainty
 - A (Simple) Representation for All Acts
- ► (2) Multiple Sources and Environments
 - Use the Framework to Address Experimental Evidence (Allais and Ellsberg)
- (3) Separate Uncertainty and Attitude to Uncertainty.

State space: Ω (cardinality of the continuum.)

State space: Ω (cardinality of the continuum.)

Prizes: [*I*, *m*].

State space: Ω (cardinality of the continuum.)

Prizes: [*I*, *m*].

Domain of preference: $\mathcal{F} = \{f : \Omega \rightarrow [I, m]\}$

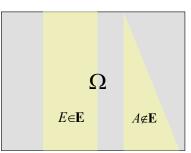
State space: Ω (cardinality of the continuum.)

Prizes: [*I*, *m*].

Domain of preference: $\mathcal{F} = \{f : \Omega \rightarrow [I, m]\}$

We axiomatize Expected Uncertain Utility (EUU).

An Example:

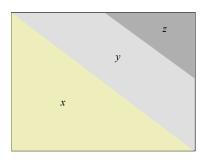


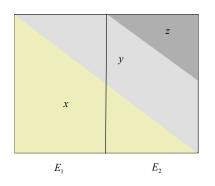
States: $\Omega = [0, 1] \times [0, 1]$

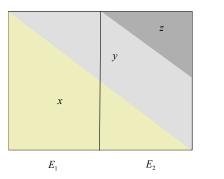
The Prior (\mathcal{E}, μ) :

 \mathcal{E} is smallest σ -algebra that contains all full-height rectangles (like E) and all sets that have zero Lebesgue measure on the square.

$$\mu([a, b] \times [0, 1]) = b - a$$
 for $b \ge a$.



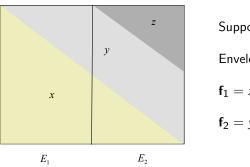




Suppose x < y < z

Envelope:

 $\mathbf{f}_1 = x$

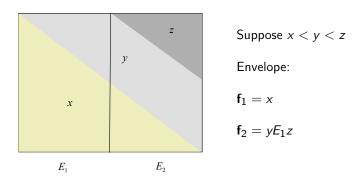


Suppose x < y < z

Envelope:

$$\mathbf{f}_1 = x$$

$$\mathbf{f}_2 = y E_1 z$$



$$U(f) = \mu(E_1)u(x, y) + \mu(E_2)u(x, z)$$

Prior: is a σ -algebra $\mathcal E$ and a non-atomic (countably additive) probability measure μ .

Prior: is a σ -algebra $\mathcal E$ and a non-atomic (countably additive) probability measure μ .

Prize intervals: $I = \{(x, y) : I \le x \le y \le m\}$

Prior: is a σ -algebra $\mathcal E$ and a non-atomic (countably additive) probability measure μ .

Prize intervals: $I = \{(x, y) : l \le x \le y \le m\}$

Envelope: Fix a prior (\mathcal{E}, μ) . For any act f, \mathbf{f}_1 is the largest measurable lower bound of f and \mathbf{f}_2 is the smallest measurable lower bound of f.

Prior: is a σ -algebra \mathcal{E} and a non-atomic (countably additive) probability measure μ .

Prize intervals: $I = \{(x, y) : I \le x \le y \le m\}$

Envelope: Fix a prior (\mathcal{E}, μ) . For any act f, \mathbf{f}_1 is the largest measurable lower bound of f and \mathbf{f}_2 is the smallest measurable lower bound of f.

Definition: An envelope for $f \in \mathcal{F}$ is a function $\mathbf{f} : \Omega \to I$ such that

- 1. **f** is \mathcal{E} -measurable and $\mu(\{\mathbf{f}_1(\omega) \leq f(\omega) \leq \mathbf{f}_2(\omega)\}) = 1$
- 2. g satisfies (1) implies $\mu(\{\mathbf{g}_1(\omega) \leq \mathbf{f}_1(\omega) \leq \mathbf{f}_2(\omega) \leq \mathbf{g}_2(\omega)\}) = 1.$

Lemma 1: Let (\mathcal{E}, μ) be a prior and $f \in \mathcal{F}$. Then, f has an envelope.

Interval utility index: a continuous function $u: I \to \mathbb{R}$ such that u(x, y) > u(x', y') whenever x > x', y > y'.

Interval utility index: a continuous function $u: I \to \mathbb{R}$ such that u(x, y) > u(x', y') whenever x > x', y > y'.

Definition: The preference \succeq is an EUU if there is a prior (\mathcal{E},μ) and an interval utility index u such that

$$U(f) = \int u(\mathbf{f}_1(\omega), \mathbf{f}_2(\omega)) d\mu$$

represents \succeq .

Given the prior μ we can define a bicumulative over prizes for every act f:

Bicumulative: Let $H_f(x, y) = \mu({\mathbf{f}_1 \le x, \mathbf{f}_2 \le y}).$

Given the prior μ we can define a bicumulative over prizes for every act f:

Bicumulative: Let $H_f(x, y) = \mu(\{\mathbf{f}_1 \le x, \mathbf{f}_2 \le y\})$. EUU: $U(f) = \int u(x, y) dH_f(x, y)$

The bicumulative is analogous to cdf over prizes in the standard case.

We provide a representation theorem for EUU preferences:

We provide a representation theorem for EUU preferences:

Under suitable assumptions,

A preference \succeq on ${\mathcal F}$ has an EUU representation:

$$U(f) = \int u(\mathbf{f}_1(\omega), \mathbf{f}_2(\omega)) d\mu$$

We provide a representation theorem for EUU preferences:

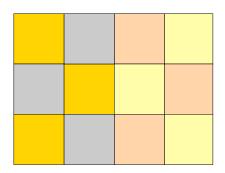
Under suitable assumptions,

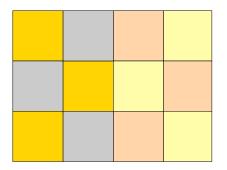
A preference \succeq on $\mathcal F$ has an EUU representation:

$$U(f) = \int u(\mathbf{f}_1(\omega), \mathbf{f}_2(\omega)) d\mu$$

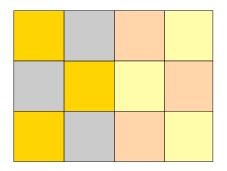
or equivalently

$$U(f) = \int u(x, y) dH_f(x, y)$$

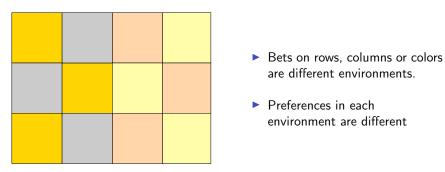




 Bets on rows, columns or colors are different environments.



- Bets on rows, columns or colors are different environments.
- Preferences in each environment are different



Each urn (or collection of events: rows, columns and colors) is a a source and the collection of all bets (acts) that depend on a particular source is an environment.

The DM can be more risk averse when betting on columns than when betting on colors.

Sources and Environments

- Let C be a collection of sets (a λ -system).
- $\blacktriangleright \mathcal{F}_{\mathcal{C}} = \{ f \in \mathcal{F} : f \text{ is } \mathcal{C} \text{measurable} \}$

For example, let

 $C_1 = \{G(ray), O(range), Y(ellow), P(each)\}$

 $\mathcal{C} = \{ \text{all events that depend only on color, G, Y, G \cup Y \text{ etc.} } \}$

 $\mathcal{F}_{\mathcal{C}} = \{ \mathsf{all acts that depend only on color} \}$

- Suppose each color has the same probability and each column K_i has the same probability (1/4).
- Consider the two bets: 100Y0 and $100K_10$.
- Suppose the DM utility function satisfies

 $U(40) = U(100Y0) > U(100K_10) = U(35)$

Hence, the DM prefers betting on color to betting on column. Equivalently the DM is more risk averse when betting on columns than when betting on colors.

- If (\mathcal{C}, π) is a probability measure (Assessment), then each $f \in \mathcal{F}_{\mathcal{C}}$ can be assigned a cdf (Lottery) G^{f} (Reduction).
- The Assessment) makes $f \in \mathcal{F}_{\mathcal{C}}$ into a source and $\mathcal{F}_{\mathcal{C}}$ into an environment.
- Then, the DM has a lottery preference V so that he assigns utility V(G^f) to each f.

Whether or not $\mathcal{F}_{\mathcal{C}}$ is an environment is subjective as is the lottery preference V on $\mathcal{F}_{\mathcal{C}}$.

Sources, Environments and EUU

- So far, the definitions of Source and Environment don't require EUU preferences.
- ► How many sources does a typical EUU preference have?
- What kind of lottery preferences does an EUU preference have in these environments?
- How do these environments enable EUU theory to address experimental and empirical evidence (Allais, Ellsberg, Home Bias)?

Definition: *u* is strongly symmetric if it has the form

$$u(x, y) = (v(x) + v(y))/2$$

for some v.

Definition: *u* is strongly symmetric if it has the form

$$u(x, y) = (v(x) + v(y))/2$$

for some v.

Lemma 3: If $\mathcal{F}_{\mathcal{C}}$ is an environment for the EUU (\mathcal{E}, μ, u) and u is not strongly symmetric, then it is an environment every EUU with the same prior.

Definition: *u* is strongly symmetric if it has the form

$$u(x, y) = (v(x) + v(y))/2$$

for some v.

Lemma 3: If $\mathcal{F}_{\mathcal{C}}$ is an environment for the EUU (\mathcal{E}, μ, u) and u is not strongly symmetric, then it is an environment every EUU with the same prior.

• EUU's with the same prior have (essentially) the same environments.

Definition: *u* is strongly symmetric if it has the form

$$u(x, y) = (v(x) + v(y))/2$$

for some v.

Lemma 3: If $\mathcal{F}_{\mathcal{C}}$ is an environment for the EUU (\mathcal{E}, μ, u) and u is not strongly symmetric, then it is an environment every EUU with the same prior.

- EUU's with the same prior have (essentially) the same environments.
- ▶ This is the sense in which (3) Separation is achieved.

Definition: *u* is strongly symmetric if it has the form

$$u(x, y) = (v(x) + v(y))/2$$

for some v.

Lemma 3: If $\mathcal{F}_{\mathcal{C}}$ is an environment for the EUU (\mathcal{E}, μ, u) and u is not strongly symmetric, then it is an environment every EUU with the same prior.

- EUU's with the same prior have (essentially) the same environments.
- ▶ This is the sense in which (3) Separation is achieved.
- ▶ We call *F_C* a Regular Environment for (*E*, *µ*) if it is an environment for some (*E*, *µ*, *u*) with *u* not strongly symmetric.

Multiple Environments

Allow EUU to

model source preference ("home bias");

Multiple Environments

Allow EUU to

- model source preference ("home bias");
- match Ellsberg-type evidence.

Multiple Environments

Allow EUU to

- model source preference ("home bias");
- match Ellsberg-type evidence.
- ► address Allais-type evidence.

Multiple Environments: Some Properties

- ► Every EUU has every source.
- ▶ The prior alone determines if $\mathcal{F}_{\mathcal{C}}$ is an environment for (\mathcal{E}, μ, u) .
- Risk attitude depends u.

.

- One environment for the the EUU (\mathcal{E}, μ, u) is $\mathcal{F}_{\mathcal{E}}$, the Ideal environment.
- Every EUU is an expected utility maximizer in its ideal environment.

$$U(f) = \int u(f(\omega), f(\omega)) d\mu$$

Multiple Environments: Some Properties

- ► Every EUU has every source.
- The prior alone determines if $\mathcal{F}_{\mathcal{C}}$ is an environment for (\mathcal{E}, μ, u) .
- Risk attitude depends *u*.
- ► One environment for the the EUU (*E*, *µ*, *u*) is *F*_{*E*}, the Ideal environment.
- Every EUU is an expected utility maximizer in its ideal environment.

$$U(f) = \int u(f(\omega), f(\omega)) d\mu$$

▶ In other environments, the EUU (\mathcal{E}, μ, u) is a nonexpected utility maximizer

Regular Environments and Lottery Preferences for EUU

Proposition 2: For any interval utility u, there exists a sequence of lottery preferences V_n^u and for any regular environment \mathcal{F}_C of (\mathcal{E}, μ) , there exists a sequence $a_n \geq 0$, $\sum a_n = 1$ such that

$$U(f) = V(G^f) = \sum_n a_n V_n^u(G^f)$$

represents (\mathcal{E}, μ, u) .

Regular Environments and Lottery Preferences for EUU

Proposition 2: For any interval utility u, there exists a sequence of lottery preferences V_n^u and for any regular environment \mathcal{F}_C of (\mathcal{E}, μ) , there exists a sequence $a_n \ge 0$, $\sum a_n = 1$ such that

$$U(f) = V(G^f) = \sum_n a_n V_n^u(G^f)$$

represents $(\mathcal{E},\mu,u).$ Furthermore, for any such sequence a_n and (\mathcal{E},μ) , there exists a regular environment $\mathcal{F}_{\mathcal{C}}$ such that

$$U(f) = \sum_{n} a_n V_n(G^f)$$

for all $f \in \mathcal{F}_{\mathcal{C}}$.

Allais and Uncertainty Aversion

Allais Paradox:

V(100) > V(150, 4/5; 0, 1/5)

but

V(100, 2/5; 0, 3/5) < V(150, 1/2; 0, 1/2)

Allais Reversals

Definition: A lottery preference V is prone to Allais-reversals if there is an environment γ so that we can find

- ► a lottery F
- prizes x, y where x is weakly worse than all other prizes in the support of F

Allais Reversals

Definition: A lottery preference V is prone to Allais-reversals if there is an environment γ so that we can find

- ► a lottery F
- prizes x, y where x is weakly worse than all other prizes in the support of F

so that we have

► V(y) > V(F)

Allais Reversals

Definition: A lottery preference V is prone to Allais-reversals if there is an environment γ so that we can find

- ► a lottery F
- prizes x, y where x is weakly worse than all other prizes in the support of F
- ▶ $\alpha \in (0, 1)$

so that we have

- ► V(y) > V(F)
- $\blacktriangleright V(\alpha y + (1 \alpha)x) < V(\alpha F + (1 \alpha)x).$

The following lottery preferences generate Allais Reversals:

The following lottery preferences generate Allais Reversals:

PTF: $\gamma: [0,1] \rightarrow [0,1]$ is a probability transformation function if it is continuous, onto and strictly increasing.

The following lottery preferences generate Allais Reversals:

 $\begin{array}{ll} \mathsf{PTF:} & \gamma:[0,1] \to [0,1] \text{ is a probability transformation function if it is}\\ \text{continuous, onto and strictly increasing.} \end{array}$

RDEU: The lottery preference $V : \mathcal{L} \to R$ is an RDEU if

$$V(F) = \int v(x) d\gamma(F(x))$$

for some PTF γ .

The following lottery preferences generate Allais Reversals:

PTF: $\gamma : [0, 1] \rightarrow [0, 1]$ is a probability transformation function if it is continuous, onto and strictly increasing.

RDEU: The lottery preference $V : \mathcal{L} \rightarrow R$ is an RDEU if

$$V(F) = \int v(x) d\gamma(F(x))$$

for some PTF γ .

PTF's that have an inverted *S*-shape are (a) consistent with Allais reversals and (b) have some supporting experimental evidence (Starmer (2000)).

Polynomial Utility and Special Cases

Recall: A sequence $a_n \ge 0$ such that $\sum_n a_n = 1$ characterizes a regular environment and in each environment $\{a_n\}$ the EUU with interval utility u has lottery preference

$$U(f) = \sum_{n} a_n V_n^u(G^f)$$

We call the sequence a_n the uncertainty measure of the corresponding environment.

• $V_1^u(G) = \int u(x, x) dG(x)$. Hence V_1^u is an EU preference. The environment $a_1 = 1$ is an EU environment.

- $V_1^u(G) = \int u(x, x) dG(x)$. Hence V_1^u is an EU preference. The environment $a_1 = 1$ is an EU environment.
- $V_n^u(G) = \int v(x) d(G(x))^n$ whenever u(x, y) = v(x) for some v. Hence, for such u, every environment is a RDEU environment.

- $V_1^u(G) = \int u(x, x) dG(x)$. Hence V_1^u is an EU preference. The environment $a_1 = 1$ is an EU environment.
- $V_n^u(G) = \int v(x) d(G(x))^n$ whenever u(x, y) = v(x) for some v. Hence, for such u, every environment is a RDEU environment.
- More generally, whenever u(x, y) = αv(x) + (1 α)v(y) for some v, every environment is an RDEU environment. This RDEU has the desired inverted S-shape whenever {a_n} is sufficiently uncertain.

- $V_1^u(G) = \int u(x, x) dG(x)$. Hence V_1^u is an EU preference. The environment $a_1 = 1$ is an EU environment.
- $V_n^u(G) = \int v(x) d(G(x))^n$ whenever u(x, y) = v(x) for some v. Hence, for such u, every environment is a RDEU environment.
- More generally, whenever u(x, y) = αv(x) + (1 α)v(y) for some v, every environment is an RDEU environment. This RDEU has the desired inverted S-shape whenever {a_n} is sufficiently uncertain.
- V^u₂ is the quadratic utility of Machina (1982), Chew, Epstein and Segal (1991) (with utility index u). Hence, a₂ = 1 is the quadratic utility environment.

Strong Uncertainty Aversion

An EUU is risk averse in an environment if it dislikes mean preserving spreads.

Strong Uncertainty Aversion

An EUU is risk averse in an environment if it dislikes mean preserving spreads.

An EUU is strongly uncertainty averse if it is risk averse in every environment.

Strong Uncertainty Aversion

An EUU is risk averse in an environment if it dislikes mean preserving spreads.

An EUU is strongly uncertainty averse if it is risk averse in every environment.

► u is maximally pessimistic if there exist some v such that u(x, y) = v(x) for all x, y. Proposition 3: Let (\mathcal{E},μ,u) be an EUU. Then, the following conditions are equivalent

- (1) The EUU (\mathcal{E}, μ, u) is strongly uncertainty averse;
- (2) u is maximally pessimistic and concave.

Uncertainty of Environments

Definition: The environment $\mathcal{F}_{\mathcal{A}}$ is more uncertain than the environment $\mathcal{F}_{\mathcal{B}}$ if every strongly uncertainty averse EUU prefers $f \in \mathcal{F}_{\mathcal{A}}$ to $g \in \mathcal{F}_{\mathcal{B}}$ whenever f and g yield the same lottery.

$$\sum_n b_n t^n \le \sum_n a_n t^n$$

for all $t \in [0, 1]$, where $\{a_n\}$ and $\{b_n\}$ are the uncertainty measures of $\mathcal{F}_{\mathcal{A}}$ and $\mathcal{F}_{\mathcal{B}}$ respectively.

- We write $\mathcal{F}_{\mathcal{B}} \succeq_{mu} \mathcal{F}_{\mathcal{A}}$ (or equivalently $\{b_n\} \succeq_{mu} \{a_n\}$) to mean " $\mathcal{F}_{\mathcal{B}}$ is more uncertain than $\mathcal{F}_{\mathcal{A}}$."
- $b_{n+1} = 1$ and $a_n = 1$ implies $\{b_n\} \succeq_{mu} \{a_n\}$.
- Not all environments can be ranked. For example, a₂ = 1 and a₁ = a₄ = 1/2 cannot be ranked.

Risk Loving under Extreme Uncertainty:

The EUU is risk loving under extreme uncertainty if, for sufficiently uncertain environments, there are lotteries that the DM prefers to their expected value.

Definition *u* displays risk loving under extreme uncertainty if there exists an environment $\mathcal{F}_{\mathcal{A}}$ and a lottery *F* such that $\mathcal{F}_{\mathcal{B}} \succeq_{mu} \mathcal{F}_{\mathcal{A}}$ implies U(f) > U(z) whenever $f \in \mathcal{F}_{\mathcal{B}}$, $G^f = F$ and *z* is the mean of *F*.

Proposition 5: The following conditions are equivalent

u is not maximally pessimistic;

Proposition 5: The following conditions are equivalent

- u is not maximally pessimistic;
- ► *u* is prone to Allais-reversals;

Proposition 5: The following conditions are equivalent

- u is not maximally pessimistic;
- ► *u* is prone to Allais-reversals;
- *u* displays risk loving under extreme uncertainty.

Ellsberg One Urn Example

3 balls, red, blue or green. 1 ball is red. Intuitively, $\{r\}$ and $\{b, g\}$ have unambiguous probability 1/3 and 2/3. But, $\{g\}$ and $\{r, b\}$ are ambiguous.

What would it mean for a model (an EUU model) to *explain* or *rationalize* the Ellsberg One-Urn Example?

- *N* is a nonempty finite set; \mathcal{N} is the set of subsets of *N*.
- *P* be the set of all probabilities on \mathcal{N} and $\iota \in P$.
- $\mathcal{M} \subset \mathcal{N}$ is a collection of sets (a λ -system).

The collection (N, \mathcal{M}, ι) is an urn experiment if for all $K \in \mathcal{N} \setminus \mathcal{M}$, there exist $p \in P$ such that $p(M) = \iota(M)$ for all $M \in \mathcal{M}$ and $p(K) \neq \iota(K)$.

Given any prior (\mathcal{E}, μ) , a collection of subsets \mathcal{C}_o of Ω is unambiguous if there exists a source \mathcal{A} such that $\mathcal{C}_o \subset \mathcal{A}$. The event $\mathcal{A} \subset \Omega$ is ambiguous wrt \mathcal{C}_o if there exists no source \mathcal{B} such that $\mathcal{C}_o \cup \{\mathcal{A}\} \subset \mathcal{B}$.

Ellsberg One Urn Example is an Urn Example

 $\mathcal{M} = \{\{r\}, \{b, g\}\}$ ι is any probability such that $\iota\{r\} = 1/3$ and $\iota\{b, g\} = 2/3$

Zhang's (1997) 4 color urn

2 balls: red, blue, green, or yellow.1 balls is red or blue1 ball is red or green.

Zhang's (1997) 4 color urn

2 balls: red, blue, green, or yellow.1 balls is red or blue1 ball is red or green.

Intuitively unambiguous events are $\{r, b\}$, $\{g, y\}$, $\{r, g\}$, $\{b, y\}$ and each has $\iota = 1/2$.

Rationalizing Urn Experiments

The prior (\mathcal{E}, μ) rationalizes the urn experiment (N, μ, ι) if there exists an onto mapping $T : \Omega \to N$ such that $\mathcal{C}_o := \{T^{-1}(M) \mid M \in \mathcal{M}\}$ is unambiguous and every $T^{-1}(L)$ for $L \in \mathcal{N} \setminus \mathcal{M}$ is ambiguous wrt \mathcal{C}_o .

Proposition 6: Every prior rationalizes every urn experiment.

Expected Uncertain Utility theory is a simple extension of Subjective Expected Utility theory.

Expected Uncertain Utility theory is a simple extension of Subjective Expected Utility theory.

EUU provides:

► a model of source preference.

Expected Uncertain Utility theory is a simple extension of Subjective Expected Utility theory.

EUU provides:

- ► a model of source preference.
- ▶ a unified treatment of Allais and Ellsberg style experiments.

Expected Uncertain Utility theory is a simple extension of Subjective Expected Utility theory.

EUU provides:

- ► a model of source preference.
- ▶ a unified treatment of Allais and Ellsberg style experiments.
- separation of uncertainty attitude and uncertainty perception.

Expected Uncertain Utility theory is a simple extension of Subjective Expected Utility theory.

EUU provides:

- ► a model of source preference.
- ▶ a unified treatment of Allais and Ellsberg style experiments.
- separation of uncertainty attitude and uncertainty perception.

EUU has:

 significant overlap with many existing models (Choquet EU, Maxmin EU, α-Maxmin EU.)

Expected Uncertain Utility theory is a simple extension of Subjective Expected Utility theory.

EUU provides:

- ► a model of source preference.
- > a unified treatment of Allais and Ellsberg style experiments.
- separation of uncertainty attitude and uncertainty perception.

EUU has:

- significant overlap with many existing models (Choquet EU, Maxmin EU, α-Maxmin EU.)
- few behavioral restrictions; more of a framework than a "theory."